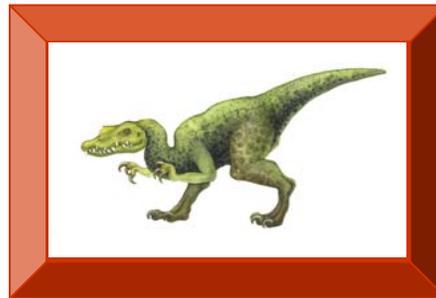


# Chapter 3: Processes





# Chapter 3: Processes

---

- Process Concept
- Process Scheduling
- Operations on Processes
- Interprocess Communication
- Examples of IPC Systems
- Communication in Client-Server Systems





# Objectives

---

- To introduce the notion of a process -- a program in execution, which forms the basis of all computation
- To describe the various features of processes, including scheduling, creation and termination, and communication
- To describe communication in client-server systems





# Process Concept

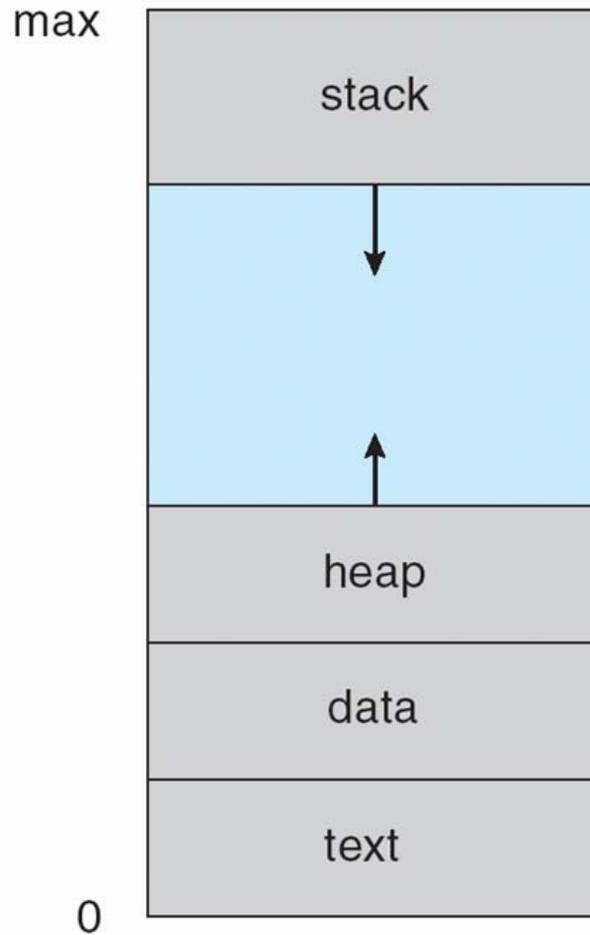
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- An operating system executes a variety of programs:
  - Batch system – jobs
  - Time-shared systems – user programs or tasks
- Textbook uses the terms *job* and *process* almost interchangeably
- Process – a program in execution; process execution must progress in sequential fashion
- A process includes:
  - program counter
  - stack
  - data section





# Process in Memory





# Process State

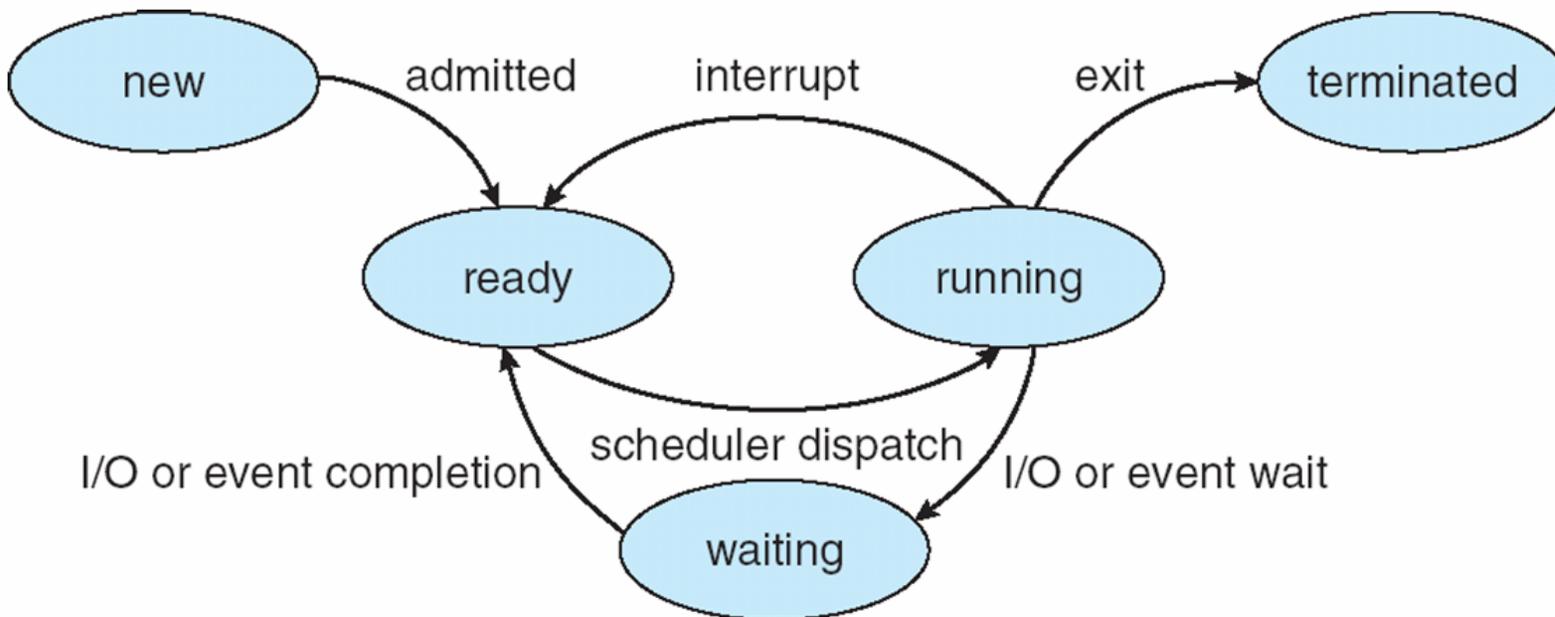
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- As a process executes, it changes *state*
  - **new**: The process is being created
  - **running**: Instructions are being executed
  - **waiting**: The process is waiting for some event to occur
  - **ready**: The process is waiting to be assigned to a processor
  - **terminated**: The process has finished execution





# Diagram of Process State





# Process Control Block (PCB)

---

Information associated with each process

- Process state
- Program counter
- CPU registers
- CPU scheduling information
- Memory-management information
- Accounting information
- I/O status information





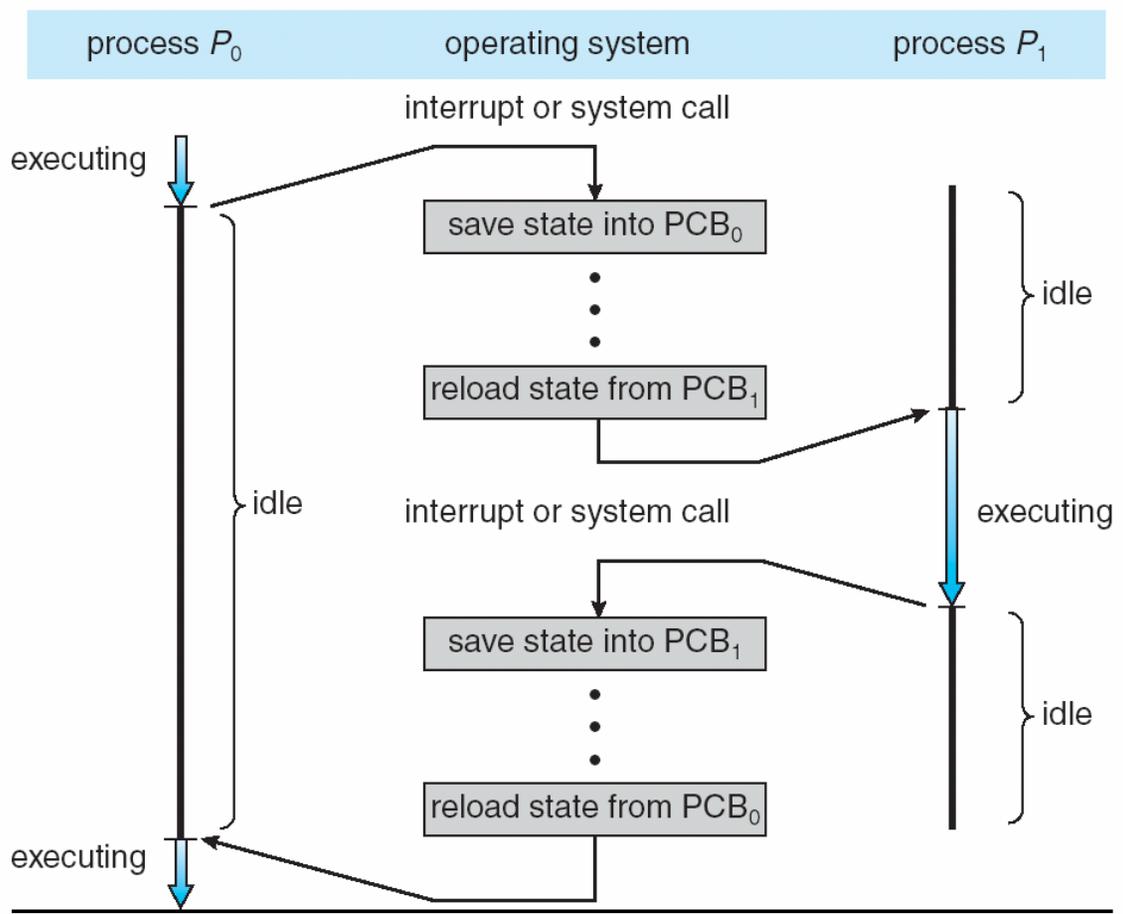
# Process Control Block (PCB)

---





# CPU Switch From Process to Process





# Process Scheduling Queues

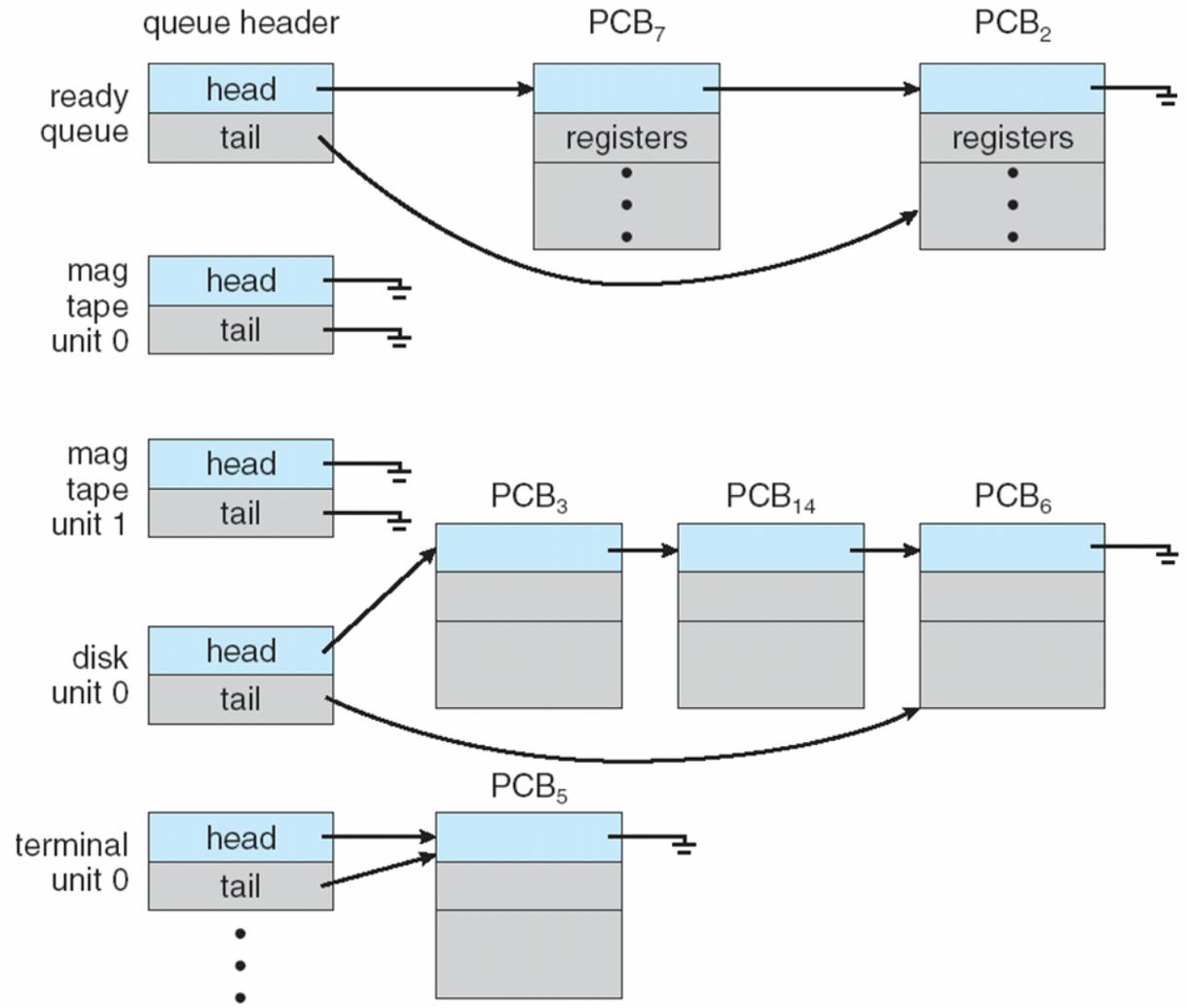
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- **Job queue** – set of all processes in the system
- **Ready queue** – set of all processes residing in main memory, ready and waiting to execute
- **Device queues** – set of processes waiting for an I/O device
- Processes migrate among the various queues



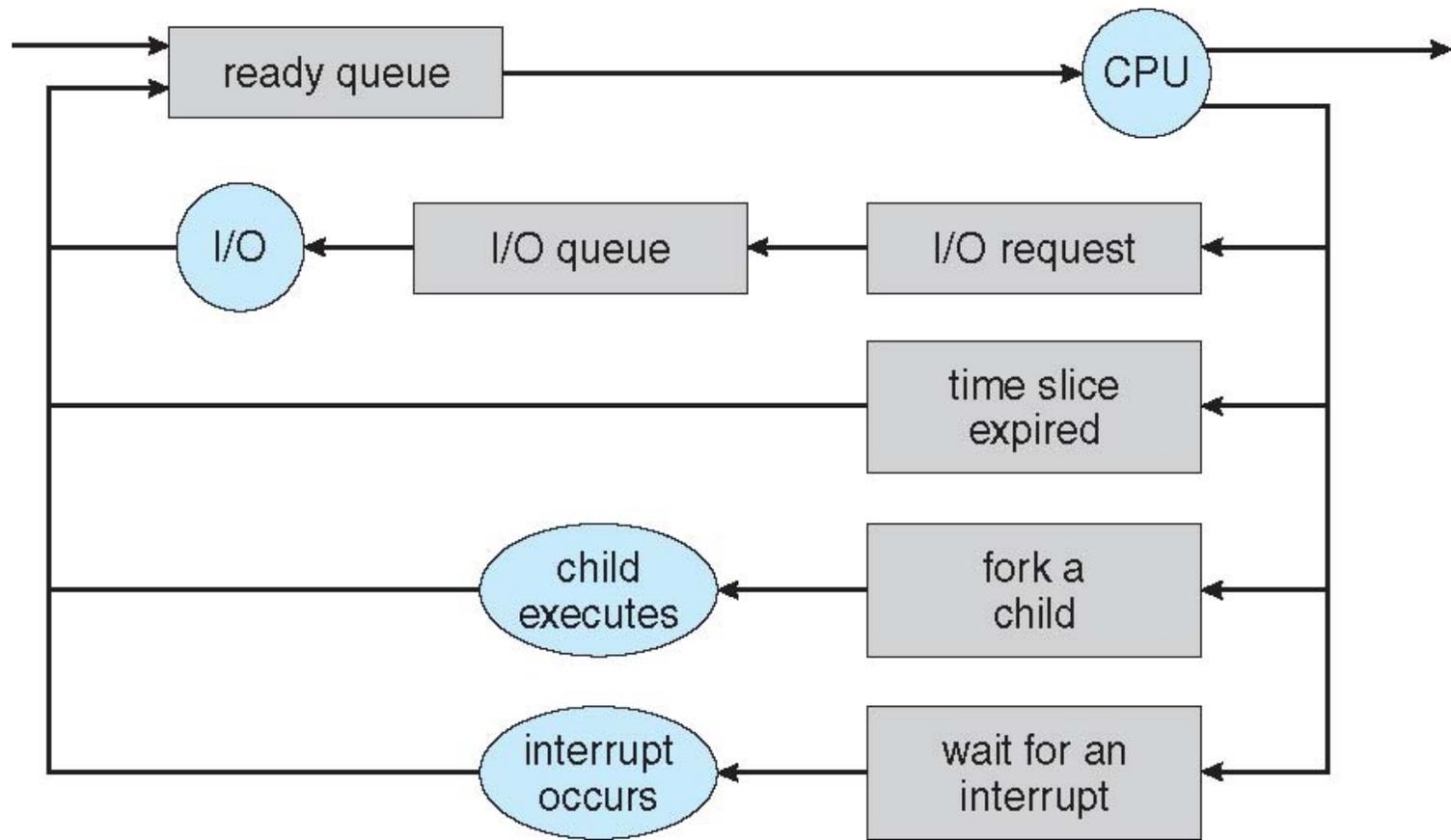


# Ready Queue And Various I/O Device Queues





# Representation of Process Scheduling





# Schedulers

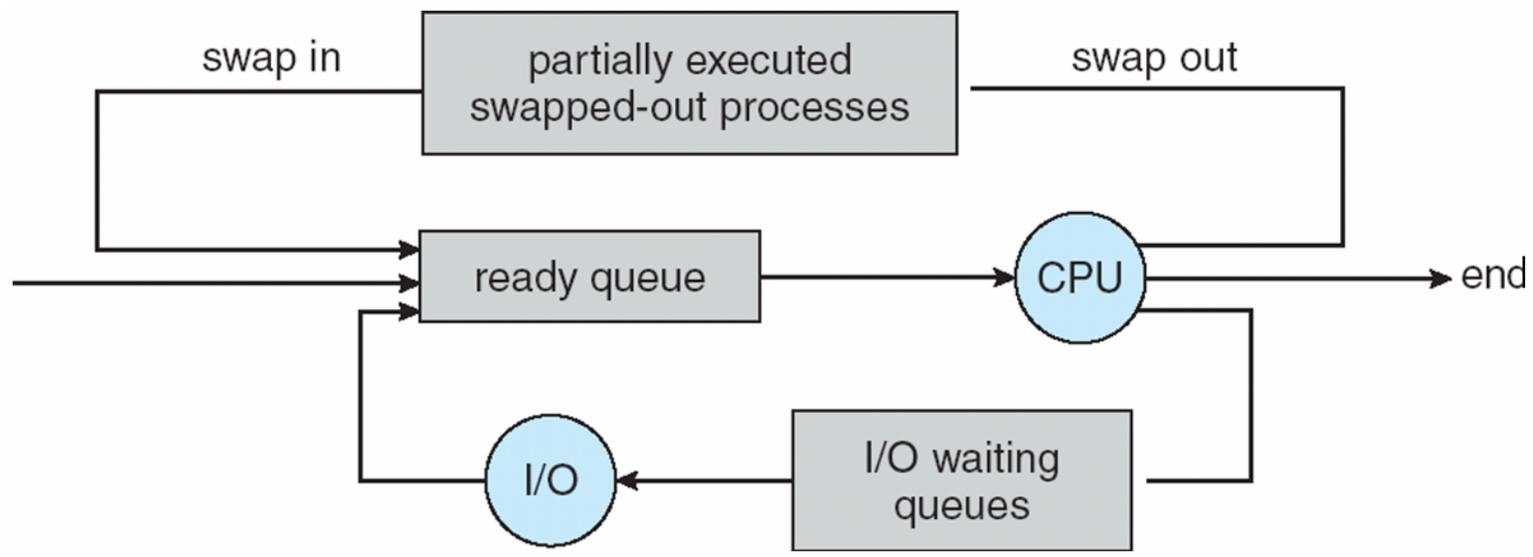
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- **Long-term scheduler** (or job scheduler) – selects which processes should be brought into the ready queue
- **Short-term scheduler** (or CPU scheduler) – selects which process should be executed next and allocates CPU





# Addition of Medium Term Scheduling





# Schedulers (Cont.)

---

- Short-term scheduler is invoked very frequently (milliseconds) ⇒ (must be fast)
- Long-term scheduler is invoked very infrequently (seconds, minutes) ⇒ (may be slow)
- The long-term scheduler controls the *degree of multiprogramming*
- Processes can be described as either:
  - **I/O-bound process** – spends more time doing I/O than computations, many short CPU bursts
  - **CPU-bound process** – spends more time doing computations; few very long CPU bursts





# Context Switch

---

- When CPU switches to another process, the system must save the state of the old process and load the saved state for the new process via a **context switch**
- **Context** of a process represented in the PCB
- Context-switch time is overhead; the system does no useful work while switching
- Time dependent on hardware support





# Process Creation

---

- **Parent** process create **children** processes, which, in turn create other processes, forming a tree of processes
- Generally, process identified and managed via a **process identifier (pid)**
- Resource sharing
  - Parent and children share all resources
  - Children share subset of parent's resources
  - Parent and child share no resources
- Execution
  - Parent and children execute concurrently
  - Parent waits until children terminate





# Process Creation (Cont.)

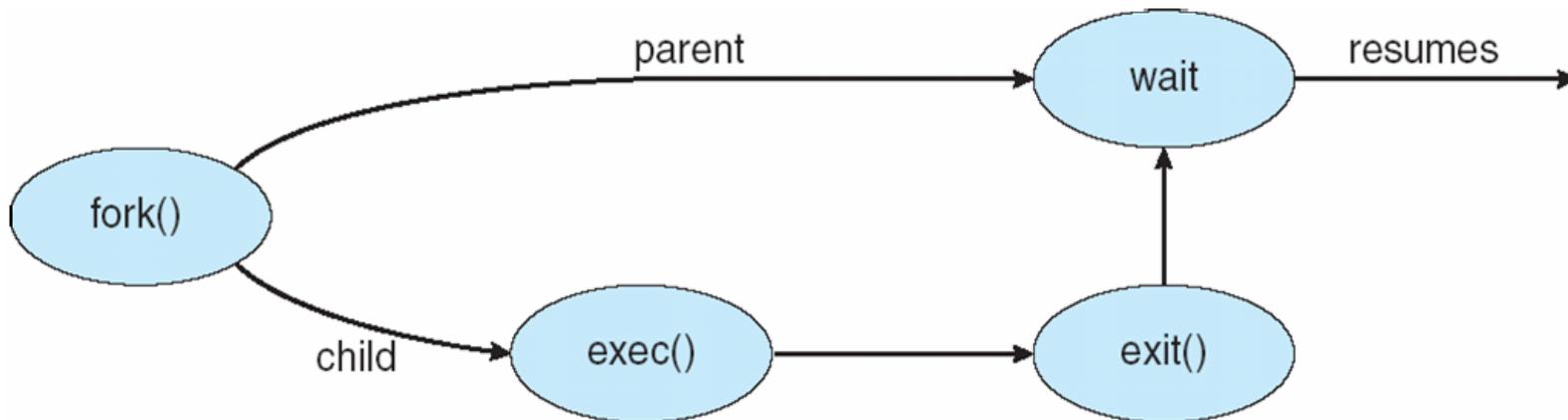
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- Address space
  - Child duplicate of parent
  - Child has a program loaded into it
  
- UNIX examples
  - **fork** system call creates new process
  - **exec** system call used after a **fork** to replace the process' memory space with a new program





# Process Creation





# C Program Forking Separate Process

---

```
int main()
{
    pid_t pid;
    /* fork another process */
    pid = fork();
    if (pid < 0) { /* error occurred */
        fprintf(stderr, "Fork Failed");
        exit(-1);
    }
    else if (pid == 0) { /* child process */
        execlp("/bin/ls", "ls", NULL);
    }
    else { /* parent process */
        /* parent will wait for the child to complete */
        wait (NULL);
        printf ("Child Complete");
        exit(0);
    }
}
```





# Process Creation in POSIX

```
#include <sys/types.h>
#include <stdio.h>
#include <unistd.h>

int main()
{
    pid_t pid;

    /* fork a child process */
    pid = fork();

    if (pid < 0) { /* error occurred */
        fprintf(stderr, "Fork Failed");
        exit(-1);
    }
    else if (pid == 0) { /* child process */
        execlp("/bin/ls", "ls", NULL);
    }
    else { /* parent process */
        /* parent will wait for the child to complete */
        wait(NULL);
        printf("Child Complete");
        exit(0);
    }
}
```





# Process Creation in Win32

---

```
#include <stdio.h>
#include <windows.h>

int main(VOID)
{
    STARTUPINFO si;
    PROCESS_INFORMATION pi;

    // allocate memory
    ZeroMemory(&si, sizeof(si));
    si.cb = sizeof(si);
    ZeroMemory(&pi, sizeof(pi));

    // create child process
    if (!CreateProcess(NULL, // use command line
        "C:\\WINDOWS\\system32\\mspaint.exe", // command line
        NULL, // don't inherit process handle
        NULL, // don't inherit thread handle
        FALSE, // disable handle inheritance
        0, // no creation flags
        NULL, // use parent's environment block
        NULL, // use parent's existing directory
        &si,
        &pi))
    {
        fprintf(stderr, "Create Process Failed");
        return -1;
    }
    // parent will wait for the child to complete
    WaitForSingleObject(pi.hProcess, INFINITE);
    printf("Child Complete");

    // close handles
    CloseHandle(pi.hProcess);
    CloseHandle(pi.hThread);
}
```





# Process Creation in Java

---

```
import java.io.*;

public class OSProcess
{
    public static void main(String[] args) throws IOException {
        if (args.length != 1) {
            System.err.println("Usage: java OSProcess <command>");
            System.exit(0);
        }

        // args[0] is the command
        ProcessBuilder pb = new ProcessBuilder(args[0]);
        Process proc = pb.start();

        // obtain the input stream
        InputStream is = proc.getInputStream();
        InputStreamReader isr = new InputStreamReader(is);
        BufferedReader br = new BufferedReader(isr);

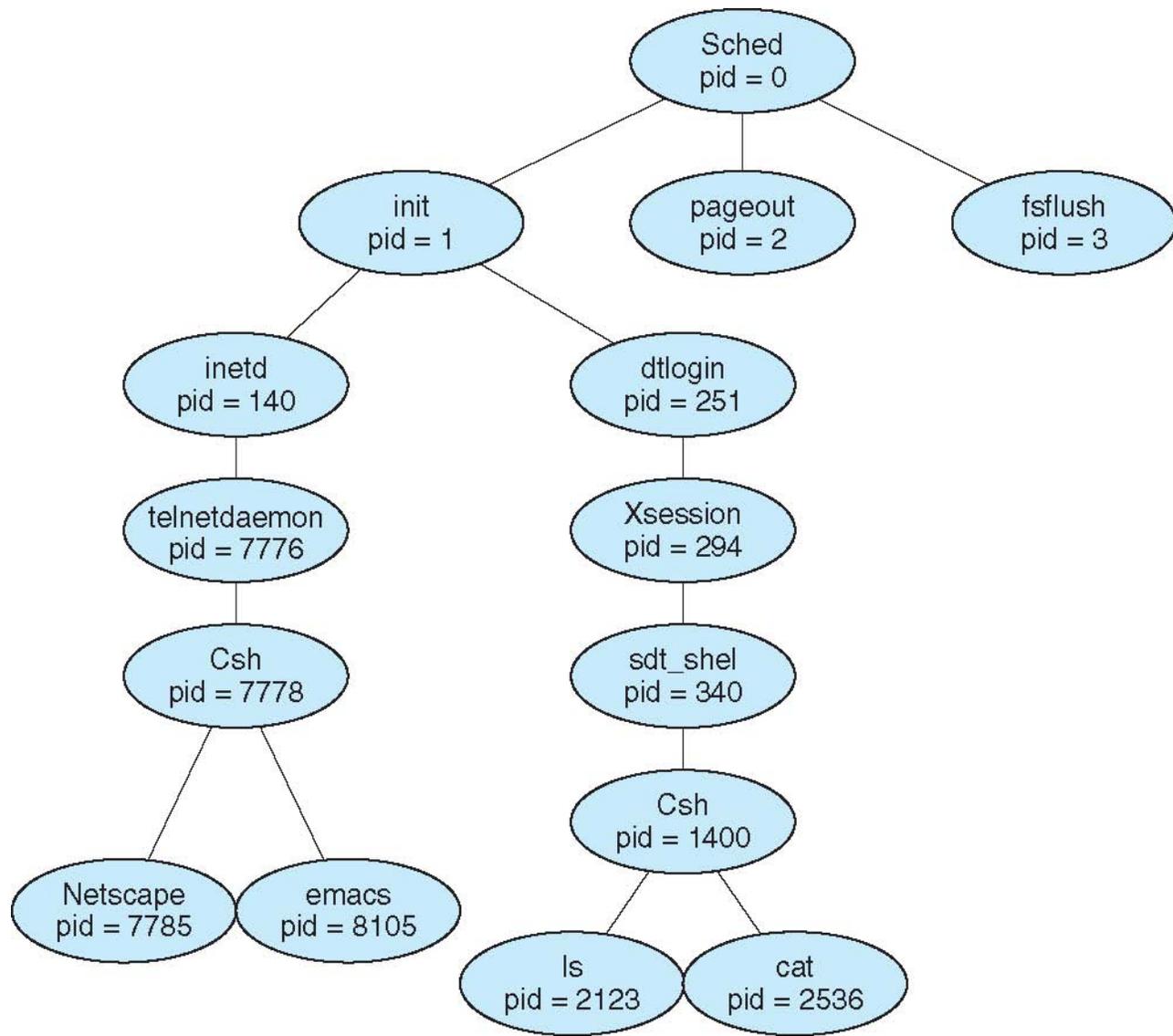
        // read what is returned by the command
        String line;
        while ( (line = br.readLine()) != null)
            System.out.println(line);

        br.close();
    }
}
```





# A tree of processes on a typical Solaris





# Process Termination

---

- Process executes last statement and asks the operating system to delete it (**exit**)
  - Output data from child to parent (via **wait**)
  - Process' resources are deallocated by operating system
  
- Parent may terminate execution of children processes (**abort**)
  - Child has exceeded allocated resources
  - Task assigned to child is no longer required
  - If parent is exiting
    - ▶ Some operating system do not allow child to continue if its parent terminates
      - All children terminated - **cascading termination**





# Interprocess Communication

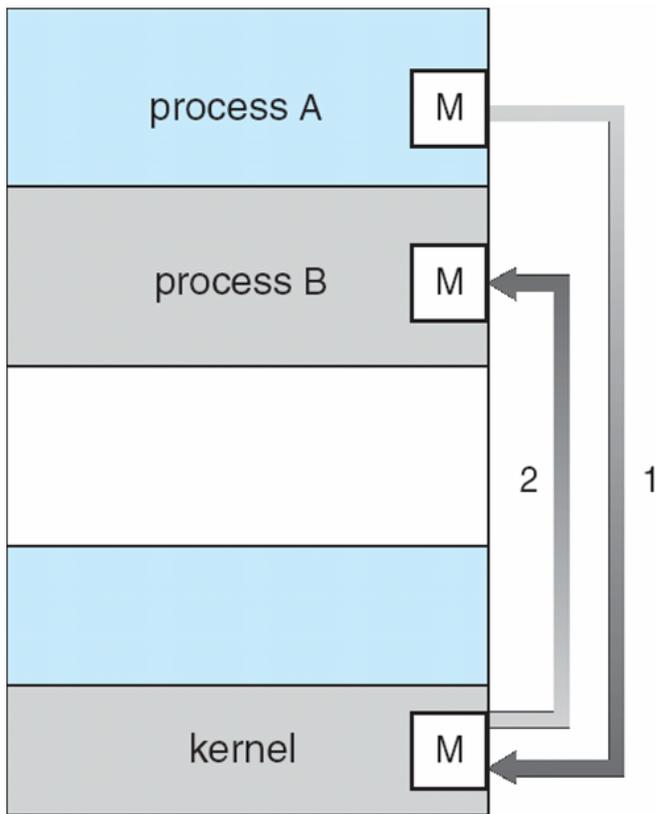
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- Processes within a system may be **independent** or **cooperating**
- Cooperating process can affect or be affected by other processes, including sharing data
- Reasons for cooperating processes:
  - Information sharing
  - Computation speedup
  - Modularity
  - Convenience
- Cooperating processes need **interprocess communication (IPC)**
- Two models of IPC
  - Shared memory
  - Message passing

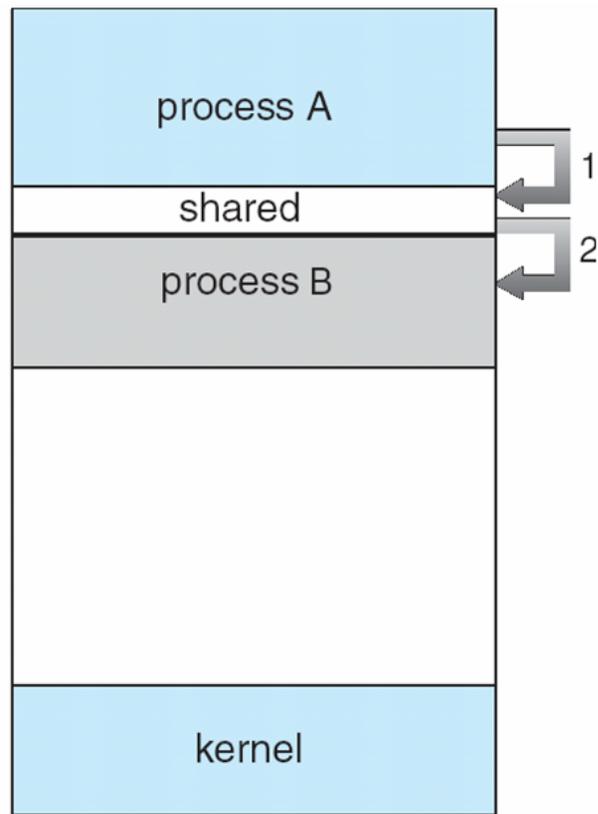




# Communications Models



(a)



(b)





# Cooperating Processes

---

- **Independent** process cannot affect or be affected by the execution of another process.
- **Cooperating** process can affect or be affected by the execution of another process.
- Advantages of process cooperation
  - Information sharing
  - Computation speed-up
  - Modularity
  - Convenience





# Producer-Consumer Problem

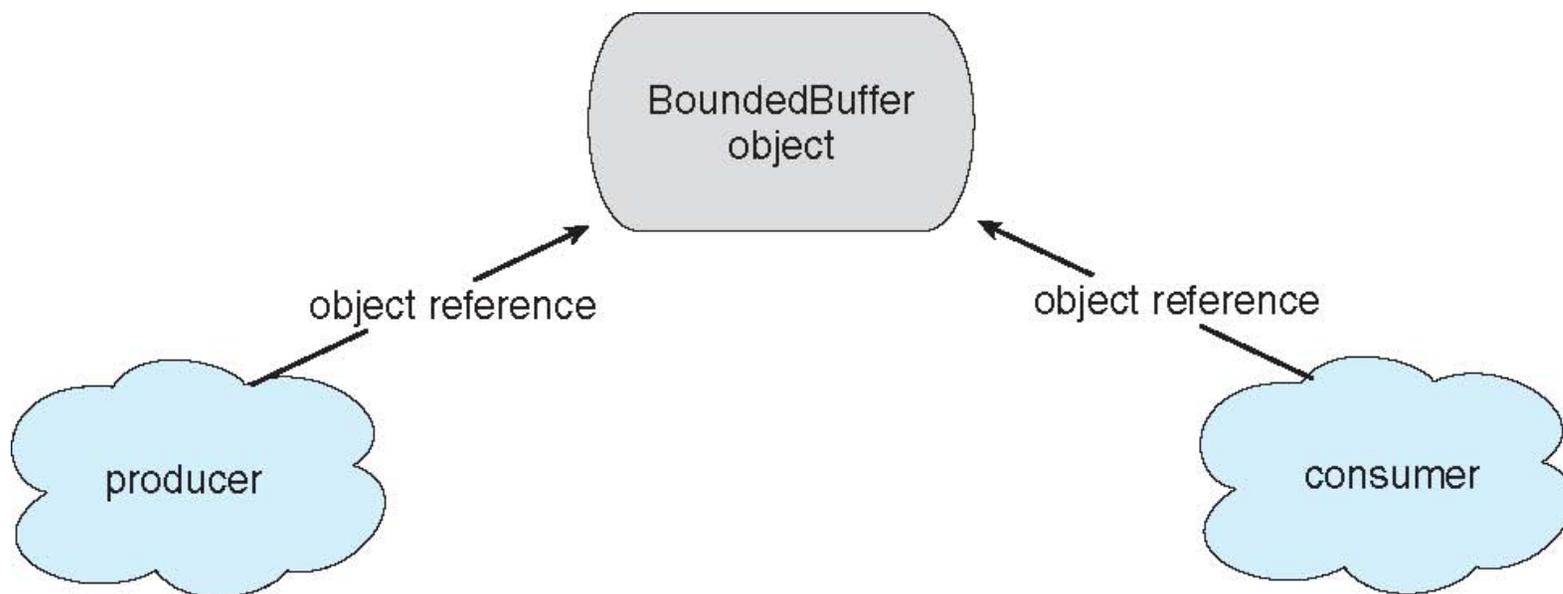
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- Paradigm for cooperating processes, *producer* process produces information that is consumed by a *consumer* process
  - *unbounded-buffer* places no practical limit on the size of the buffer
  - *bounded-buffer* assumes that there is a fixed buffer size





# Simulating Shared Memory in Java





# Bounded-Buffer – Shared-Memory Solution

---

- Shared data

```
#define BUFFER_SIZE 10
typedef struct {
    . . .
} item;

item buffer[BUFFER_SIZE];
int in = 0;
int out = 0;
```

- Solution is correct, but can only use BUFFER\_SIZE-1 elements





# Bounded-Buffer – Producer

---

```
while (true) {  
    /* Produce an item */  
    while (((in = (in + 1) % BUFFER SIZE count) == out)  
        ; /* do nothing -- no free buffers */  
    buffer[in] = item;  
    in = (in + 1) % BUFFER SIZE;  
}
```





# Bounded Buffer – Consumer

---

```
while (true) {  
    while (in == out)  
        ; // do nothing -- nothing to consume  
  
    // remove an item from the buffer  
    item = buffer[out];  
    out = (out + 1) % BUFFER SIZE;  
    return item;  
}
```





# Interprocess Communication – Message Passing

---

- Mechanism for processes to communicate and to synchronize their actions
- Message system – processes communicate with each other without resorting to shared variables
- IPC facility provides two operations:
  - **send**(*message*) – message size fixed or variable
  - **receive**(*message*)
- If  $P$  and  $Q$  wish to communicate, they need to:
  - establish a *communication link* between them
  - exchange messages via send/receive
- Implementation of communication link
  - physical (e.g., shared memory, hardware bus)
  - logical (e.g., logical properties)





# Implementation Questions

---

- How are links established?
- Can a link be associated with more than two processes?
- How many links can there be between every pair of communicating processes?
- What is the capacity of a link?
- Is the size of a message that the link can accommodate fixed or variable?
- Is a link unidirectional or bi-directional?





# Direct Communication

---

- Processes must name each other explicitly:
  - **send** ( $P, message$ ) – send a message to process P
  - **receive**( $Q, message$ ) – receive a message from process Q
  
- Properties of communication link
  - Links are established automatically
  - A link is associated with exactly one pair of communicating processes
  - Between each pair there exists exactly one link
  - The link may be unidirectional, but is usually bi-directional





# Indirect Communication

---

- Messages are directed and received from mailboxes (also referred to as ports)
  - Each mailbox has a unique id
  - Processes can communicate only if they share a mailbox
- Properties of communication link
  - Link established only if processes share a common mailbox
  - A link may be associated with many processes
  - Each pair of processes may share several communication links
  - Link may be unidirectional or bi-directional





# Indirect Communication

---

- Operations

- create a new mailbox
- send and receive messages through mailbox
- destroy a mailbox

- Primitives are defined as:

**send**(*A, message*) – send a message to mailbox A

**receive**(*A, message*) – receive a message from mailbox A





# Indirect Communication

---

## ■ Mailbox sharing

- $P_1$ ,  $P_2$ , and  $P_3$  share mailbox A
- $P_1$  sends;  $P_2$  and  $P_3$  receive
- Who gets the message?

## ■ Solutions

- Allow a link to be associated with at most two processes
- Allow only one process at a time to execute a receive operation
- Allow the system to select arbitrarily the receiver. Sender is notified who the receiver was.





# Synchronization

---

- Message passing may be either blocking or non-blocking
- **Blocking** is considered **synchronous**
  - **Blocking send** has the sender block until the message is received
  - **Blocking receive** has the receiver block until a message is available
- **Non-blocking** is considered **asynchronous**
  - **Non-blocking send** has the sender send the message and continue
  - **Non-blocking receive** has the receiver receive a valid message or null





# Buffering

---

- Queue of messages attached to the link; implemented in one of three ways
  1. Zero capacity – 0 messages  
Sender must wait for receiver (rendezvous)
  2. Bounded capacity – finite length of  $n$  messages  
Sender must wait if link full
  3. Unbounded capacity – infinite length  
Sender never waits





# Examples of IPC Systems - POSIX

---

## ■ POSIX Shared Memory

- Process first creates shared memory segment

```
segment id = shmget(IPC_PRIVATE, size, S_IRUSR | S_IWUSR);
```

- Process wanting access to that shared memory must attach to it

```
shared memory = (char *) shmat(id, NULL, 0);
```

- Now the process could write to the shared memory

```
printf(shared memory, "Writing to shared memory");
```

- When done a process can detach the shared memory from its address space

```
shmdt(shared memory);
```





# Examples of IPC Systems - Mach

---

- Mach communication is message based
  - Even system calls are messages
  - Each task gets two mailboxes at creation- Kernel and Notify
  - Only three system calls needed for message transfer  
`msg_send()`, `msg_receive()`, `msg_rpc()`
  - Mailboxes needed for communication, created via  
`port_allocate()`





# Examples of IPC Systems – Windows XP

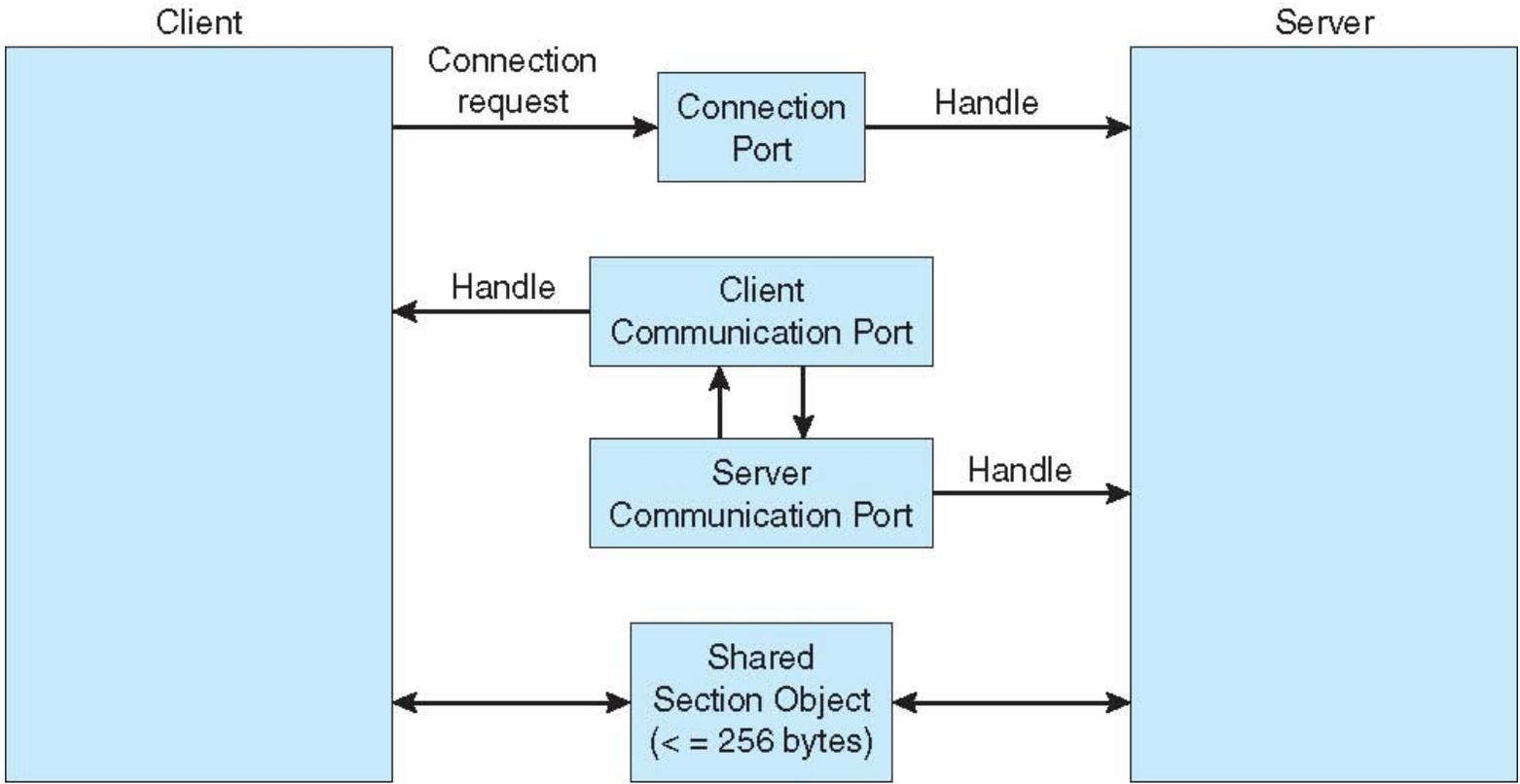
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- Message-passing centric via **local procedure call (LPC)** facility
  - Only works between processes on the same system
  - Uses ports (like mailboxes) to establish and maintain communication channels
  - Communication works as follows:
    - ▶ The client opens a handle to the subsystem's connection port object
    - ▶ The client sends a connection request
    - ▶ The server creates two private communication ports and returns the handle to one of them to the client
    - ▶ The client and server use the corresponding port handle to send messages or callbacks and to listen for replies





# Local Procedure Calls in Windows XP





# Communications in Client-Server Systems

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- Sockets
- Remote Procedure Calls
- Remote Method Invocation (Java)





# Sockets

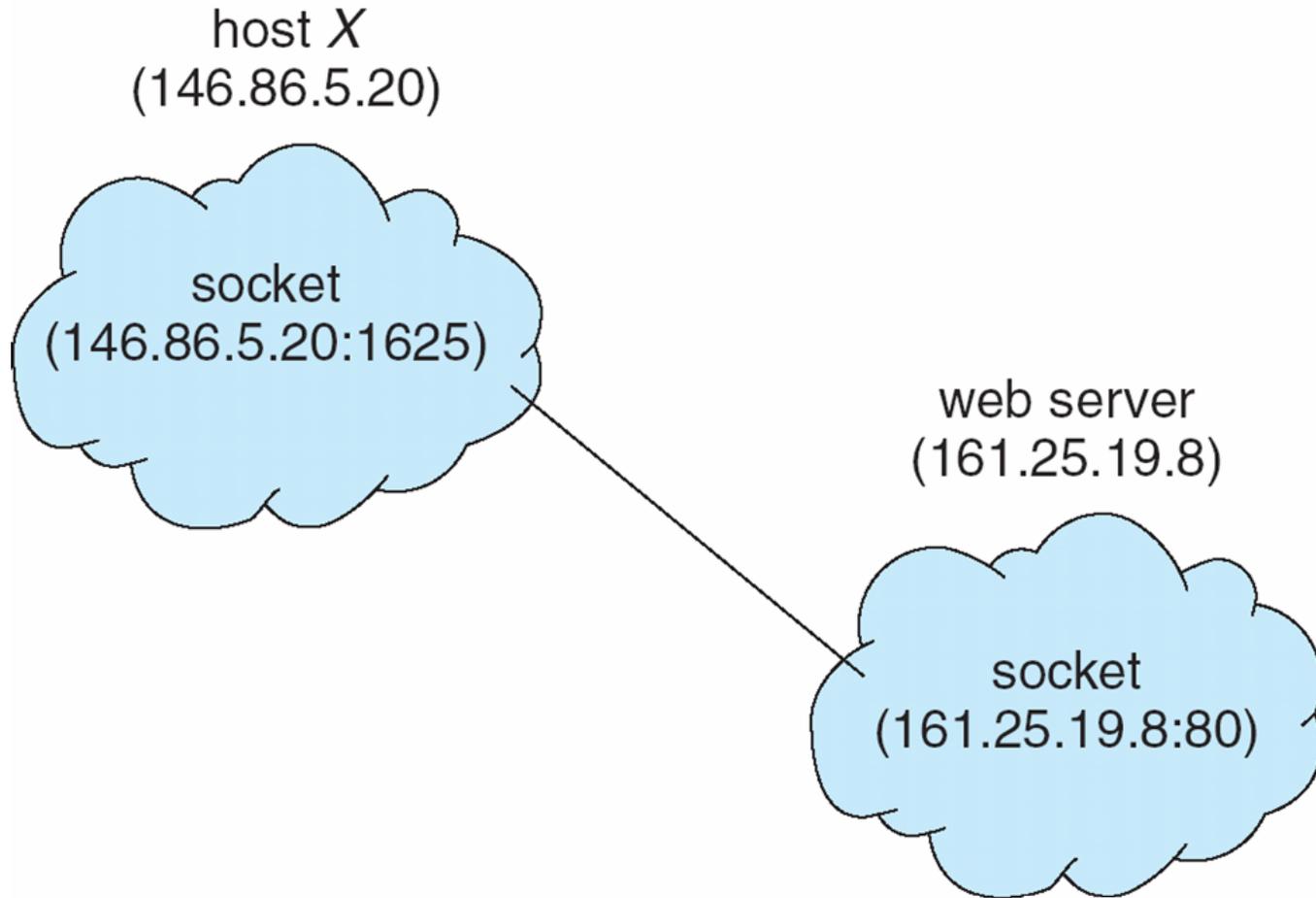
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- A socket is defined as an *endpoint for communication*
- Concatenation of IP address and port
- The socket **161.25.19.8:1625** refers to port **1625** on host **161.25.19.8**
- Communication consists between a pair of sockets





# Socket Communication





# Socket Communication in Java

---

```
public class DateServer
{
    public static void main(String[] args) {
        try {
            ServerSocket sock = new ServerSocket(6013);

            // now listen for connections
            while (true) {
                Socket client = sock.accept();

                PrintWriter pout = new
                    PrintWriter(client.getOutputStream(), true);

                // write the Date to the socket
                pout.println(new java.util.Date().toString());

                // close the socket and resume
                // listening for connections
                client.close();
            }
        }
        catch (IOException ioe) {
            System.err.println(ioe);
        }
    }
}
```





# Socket Communication in Java

---

```
public class DateClient
{
    public static void main(String[] args) {
        try {
            //make connection to server socket
            Socket sock = new Socket("127.0.0.1",6013);

            InputStream in = sock.getInputStream();
            BufferedReader bin = new
                BufferedReader(new InputStreamReader(in));

            // read the date from the socket
            String line;
            while ( (line = bin.readLine()) != null)
                System.out.println(line);

            // close the socket connection
            sock.close();
        }
        catch (IOException ioe) {
            System.err.println(ioe);
        }
    }
}
```





# Remote Procedure Calls

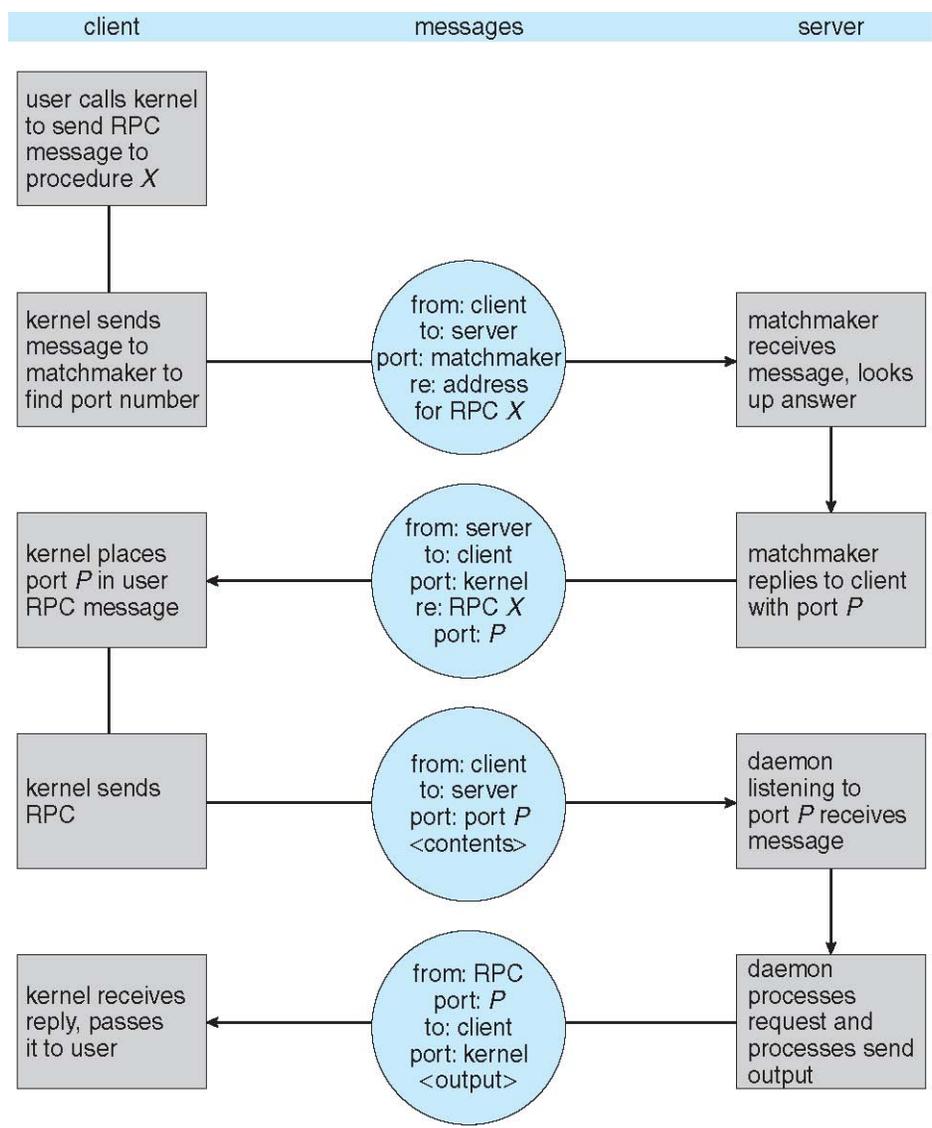
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- Remote procedure call (RPC) abstracts procedure calls between processes on networked systems
- **Stubs** – client-side proxy for the actual procedure on the server
- The client-side stub locates the server and *marshalls* the parameters
- The server-side stub receives this message, unpacks the marshalled parameters, and performs the procedure on the server





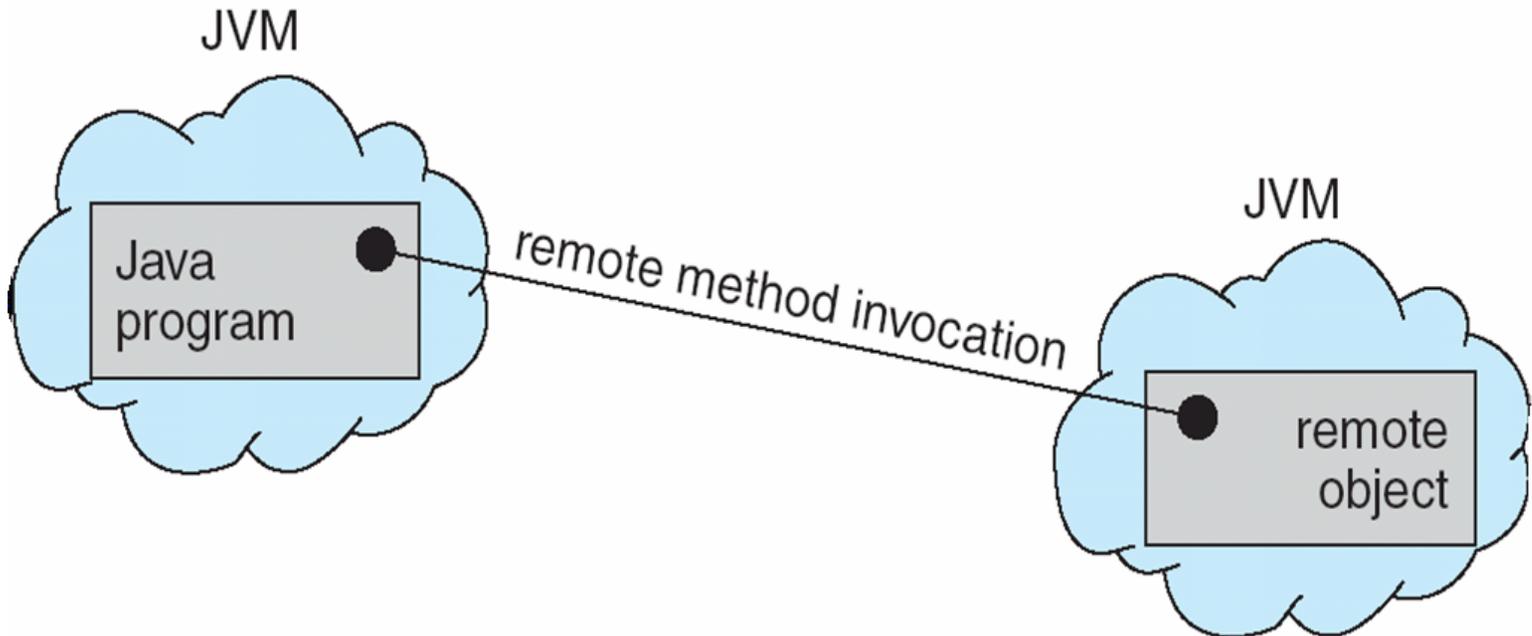
# Execution of RPC





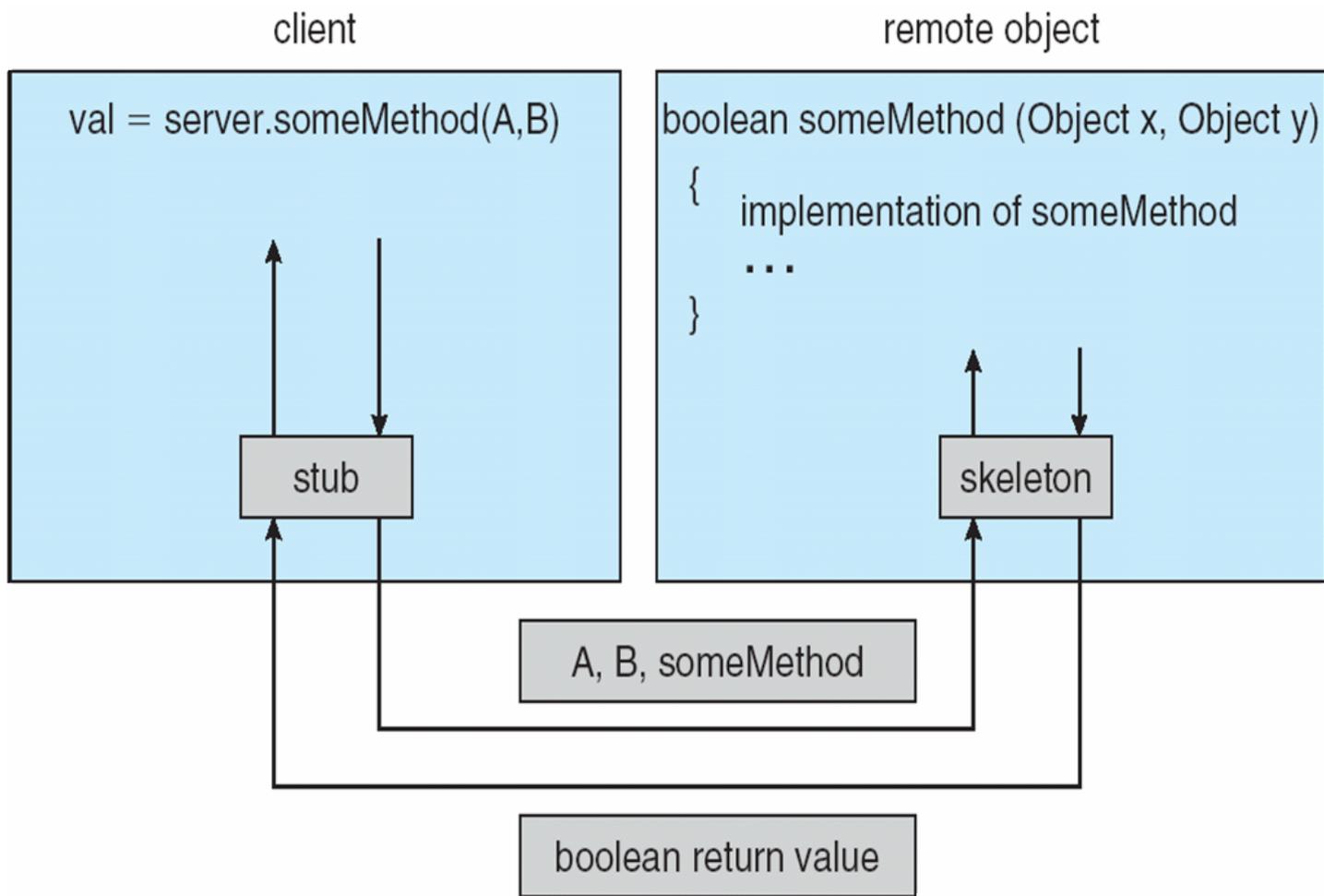
# Remote Method Invocation

- Remote Method Invocation (RMI) is a Java mechanism similar to RPCs
- RMI allows a Java program on one machine to invoke a method on a remote object





# Marshalling Parameters





# RMI Example

---

```
public interface RemoteDate extends Remote
{
    public abstract Date getDate() throws RemoteException;
}
```





# RMI Example

---

```
public class RemoteDateImpl extends UnicastRemoteObject
    implements RemoteDate
{
    public RemoteDateImpl() throws RemoteException { }

    public Date getDate() throws RemoteException {
        return new Date();
    }

    public static void main(String[] args) {
        try {
            RemoteDate dateServer = new RemoteDateImpl();

            // Bind this object instance to the name "DateServer"
            Naming.rebind("DateServer", dateServer);
        }
        catch (Exception e) {
            System.err.println(e);
        }
    }
}
```





# RMI Example

---

```
public class RMIClient
{
    public static void main(String args[]) {
        try {
            String host = "rmi://127.0.0.1/DateServer";

            RemoteDate dateServer = (RemoteDate)Naming.lookup(host);
            System.out.println(dateServer.getDate());
        }
        catch (Exception e) {
            System.err.println(e);
        }
    }
}
```



# End of Chapter 3

