

110 Systems

## **Practice Exercises**

- **12.1** State three advantages of placing functionality in a device controller, rather than in the kernel. State three disadvantages.
- **12.2** The example of handshaking in Section 12.2 used two bits: a busy bit and a command-ready bit. Is it possible to implement this handshaking with only one bit? If it is, describe the protocol. If it is not, explain why one bit is insufficient.
- **12.3** Why might a system use interrupt-driven I/O to manage a single serial port and polling I/O to manage a front-end processor, such as a terminal concentrator?
- **12.4** Polling for an I/O completion can waste a large number of CPU cycles if the processor iterates a busy-waiting loop many times before the I/O completes. But if the I/O device is ready for service, polling can be much more efficient than catching and dispatching an interrupt. Describe a hybrid strategy that combines polling, sleeping, and interrupts for I/O device service. For each of these three strategies (pure polling, pure interrupts, hybrid), describe a computing environment in which that strategy is more efficient than either of the others.
- **12.5** How does DMA increase system concurrency? How does it complicate hardware design?
- **12.6** Why is it important to scale up system-bus and device speeds as CPU speed increases?
- **12.7** Distinguish between a driver end and a stream module in a STREAMS operation.